

MESSRS:		
AGENT:		

SPECIFICATION
of
PYRO ELECTRIC PASSIVE
IN FRARED SENSOR

MODEL NO.: JH926M

APPROVED BY	CHECKED BY	DRAWN BY

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JH926M				
PART NO:		A	1/7	99
				SHANGHAI NICERA SENSOR CO.,LTD.



1. SCOPE

This specification describes a Pyroelectric Passive Infrared Sensor supplied by SHANGHAI NICERA SENSOR CO.,LTD. For passive infrared sensor device.

2. TYPE of SENSOR

2.1 TYPE NAME

Pyroelectric Passive Infrared Sensor

2.2 MODEL NO.

JH926M

3. PHYSICAL CONFIGURATION AND DIMENSIONS

3.1. APPEARANCE

There are not remarkable wounds, spots, rust and etc.

3.2. DIMENSIONS

TO-5 Package : See Fig.1.

3.3 MARKING

Lot number and model number are marked on top surface of Detector. (Figure.1)

4. GENERAL CHARACTER ISTICS

Table.1

	PARAMETER	SPECIFICATION	
4.1	Pyroelectric Passive	Balanced differential type	
	Infrared Sensor	(Series opposed type)	
4.2	Circuit Configuration	See Fig.3	

5. ELECTRICAL CHARACTERISTICS

(ENV IRONM ENT TEM PERATUER=25 (+/-) 5 DEG.C.)

Vdd=3.3V,unless specified.

Table.2

	PARAMETER	CONDITION	SPECIFICATION
5.1	Maximum range(V)		-0.3 to 3.6V
5.2	Supply Voltage (V)	Single Power Supply	2.7 to 3.3V
			(maximum rating :3.6V)
5.3	Fluctuation in Supply	Single Power Supply	Supply voltage (+/-) 3%
	Voltage		
5.4	Current Consumption	Vdd=3.3V supply	Non-Detection:20uAmax.
		Circuit after Vout is not considered	Detection :20uAmax.
5.5	Vout Output Voltage	Single Power Supply	Non-Detection: Max. 1.0 V
		*)Timing Chart : See Fig.2	Detection: Min. Vdd-1.0V
5.6	Warm-up time	*)Timing Chart : See Fig.2	Max. 30 sec.
5.7	Setting of ON TIME	*) Setting of ON TIME	Input Voltage : 0V~VddV
		: See Fig.5	
5.8	Setting of detection	*) Setting of detection performance	Input Voltage : 0V~VddV
	performance	: See Fig.6	
5.9	OEN Input		VoutOutput ON:1.0V~VddV
			VoutOutput OFF:0 ~0.6V

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6. OPTICAL CHARACTER ISTICS

Table.3

PA	RAMETER	SPECIFICATION
6.1	Field of view	X -axis: 138deg.
		Y-axis : 125 deg.
6.2	Filter substrate	Sillcon
6.3	Cut on (5%T ABS)	5 (+/-) 1 micron
6.4	Transmission	≥ 70% average 8 to 13 micron

7. ENVIROM ENTAL REQUIREM ENTS

Table.4

P/	ARAMETER	SPECIFICATION		
7.1	Operating Temperature	-20 to +70 deg. C		
7.2	Storage Temperature	-30 to +80 deg. C		
7.3	Relative Humidity	The Sensor shall operate without increase in Noise		
		Output when exposed to 90 to 95% RH at 30 deg.C		
		Continuously		
7.4	Hermeticity	The Sensor shall be sealed to withsand a vacuum level		
		of 21. 28kPa.		

8. RoHS COM PLINCE

This product conforms to the RoHS Directive in force at the date of issuance of this Specification Sheet.

9. REV IS IO N

Any revision of this specification should be made in writing by discussion

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10. NOTES

10.1. Design restrictions/precautions

If used for outdoor applications, be sure to apply suitable supplementary optical filter, drip-proof and anti-dew construction. This sensor is designed for indoor use.

In cases where secondary accidents due to operation failure or malfunctions can be anticipated, add a fail safe function to the design.

10.2. Usage restrictions/precautions

To prevent sensor malfunctions, operational failure or any deterioration of its characteristics, do not use this sensor in the following, or similar, conditions.

- A. In rapid environmental temperature changes
- B. In strong shock or vibration.
- C. In a place where there are obstructing materials(Glass, Fog, etc) through which infrared rays cannot pass within detection area.
- D. In fluid, corrosive gases and sea breeze.
- E. Continual use in high humidity atmosphere.
- F. Exposed to direct sun light or headlights of automobiles.
- G. Exposed to direct wind from a heater or air conditioner.

10.3. Assembly restrictions/precautions

Soldering

- A. Use soldering irons when soldering.
- B. Avoid keeping pins of this sensor hot for a long time as excessive heat may cause deterioration of its quality.(Ex. Within 5 sec. at 350 deg.C)

Washing

- A. Be sure to wash out all flux after soldering as remainder may cause malfunctions.
- B. Use a brush when washing . Washing with an ultrasonic cleaner may cause operational failure.

10.4. Handling and storage restrictions/precautions

To prevent sensor malfunctions, operational failure, appearance damage or any deterioration of its characteristics, do not expose this sensor to the following or similar handing and storage conditions.

- A. Vibration for a long time.
- B. Strong shock
- C. Static electricity or strong electromagnetic waves.
- D. High or Low temperature and humidity for a long time.
- E. Corrosive gases or sea breeze.
- F. Dirty and dusty environments that may contaminate the optical lens.

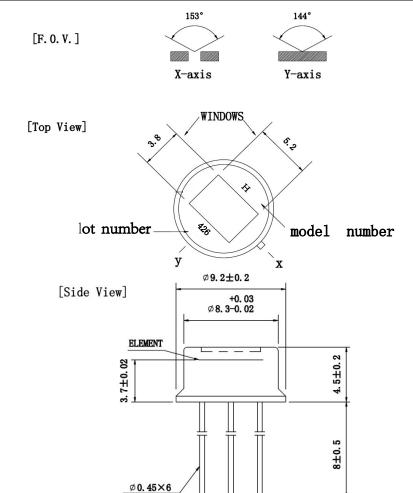
10.5. Restrictions on product use

The product described in this document shall not be used or embedded to any downstream products of which manufacture, use and/ or sales are prohibited under any applicable laws and regulations.

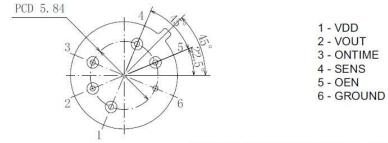
Sensor troubles resulting from misuse, inappropriate handling ro storage are not the manufacturer's responsibility.

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[Bottom View]



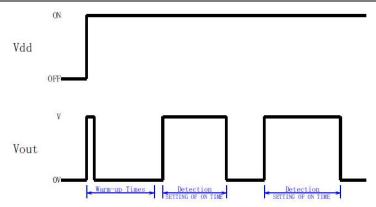
Tolerance without instruction: (+ / -) 0.2

Unit: [mm]

(*)The sensor conforms to the standard for RoHS.

Fig.1: Dimensions

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Cautions) Warm-up Time: Max. 30 sec. Regarding of detection or non-detection during the waiting time, ON signal may be made due to Instability of circuit

Fig.2: Timing Chart

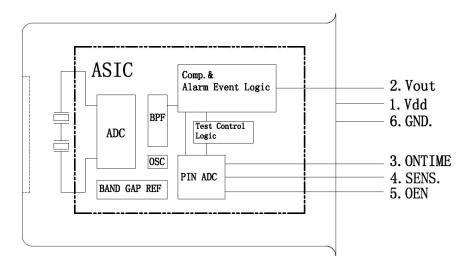


Fig.3:Circuit configuration

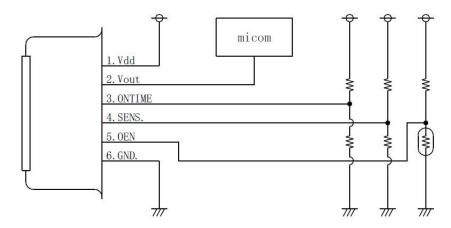
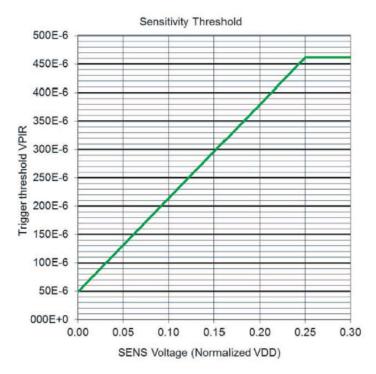


Fig.4:Basic Application Circuit Examples

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Step	ONTIME 中心值电压 (V)	ONTIME(s)	
	(VDD*(Step*2)+3)/128	(典型值)	
0	3/128 或更低	2.3	
1	(VDD*2+3)/128	4.7	
2	(VDD*4+3)/128	7	
3	(VDD*6+3)/128	9.4	
4	(VDD*8+3)/128	18. 7	
5	(VDD*10+3)/128	37	
6	(VDD*12+3)/128	56	
7	(VDD*14+3)/128	75	
8	(VDD*16+3)/128	150	
9	(VDD*18+3)/128	300	
10	(VDD*20+3)/128	449	
11	(VDD*22+3)/128	599	
12	(VDD*24+3)/128	1198	
13	(VDD*26+3)/128	2397	
14	(VDD*28+3)/128	3595	
15	(VDD*30+3)/128 或更高	4793	

Fig.5 : Setting of ON TIME



 $\label{eq:Fig.6} \textbf{Fig.6}: \textbf{Setting of detection performance}$

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